

Fluctuation relations in non-equilibrium stationary states Ising models

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Outline

- Introduction: generality about the FR

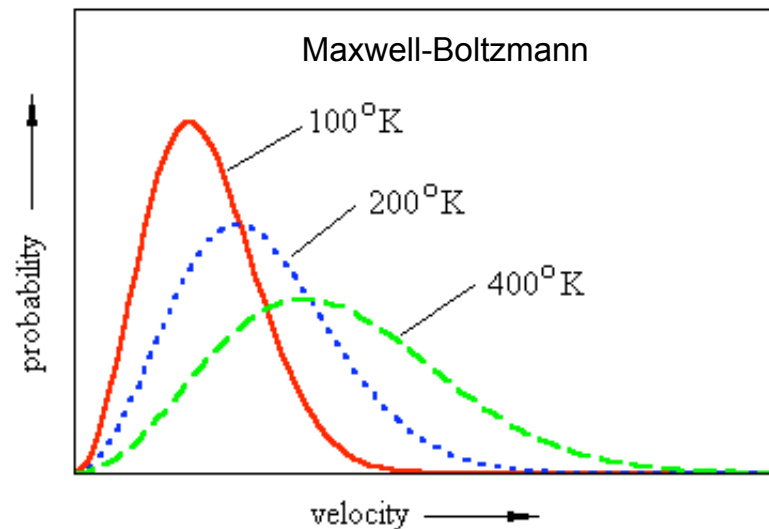
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Fluctuations in non equilibrium systems



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External driving or
thermal gradients

Motivations

- Is the FR realized in popular many degree of freedom statistical models (e.g. Ising model)?

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Heat and Work definition

DRIVING

$$Q[x] = \sum_{t=0}^{\tau-1} [E(t)_{x(t+1)} - E(t)_{x(t)}]$$

$$W[x] = \sum_{t=0}^{\tau-1} [E(t+1)_{x(t+1)} - E(t)_{x(t+1)}]$$

$$\Delta E = E(\tau)_{x(\tau)} - E(0)_{x(0)} = W + Q$$

Work moves
counter

Heat moves
counter

TWO
TEMPERATURES

$$Q_i[x] = \sum_{t=0}^{\tau-1} [E(t)_{x(t+1)} - E(t)_{x(t)}] | i$$

(where are considered only the spin-flip of spin in contact with the bath at temperature i)

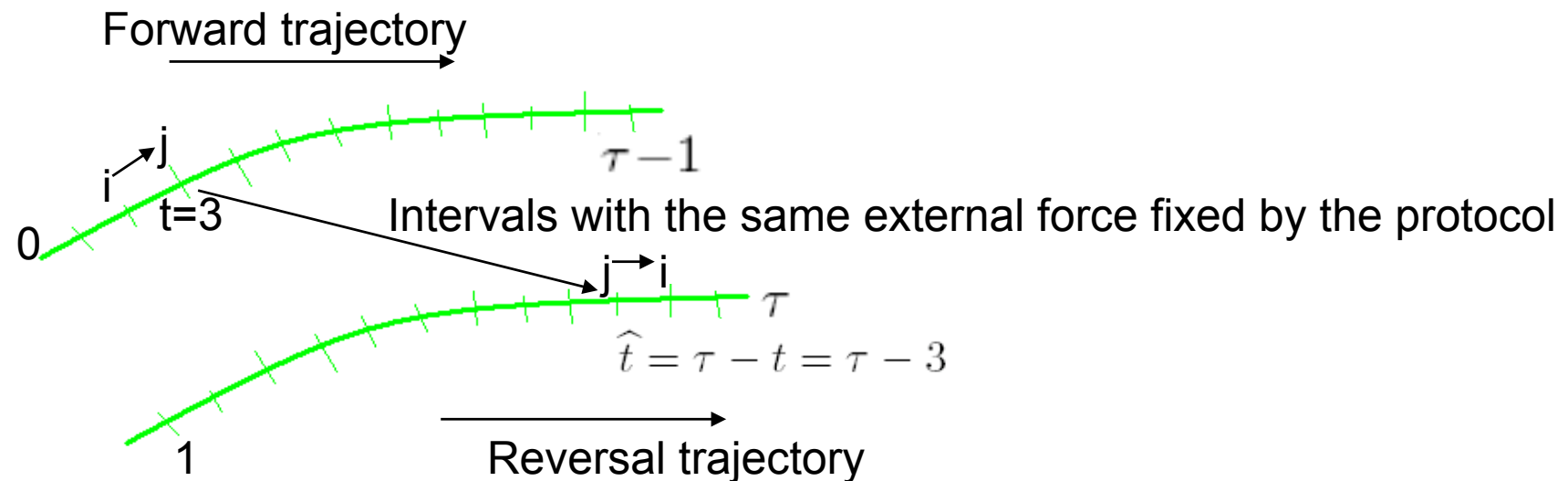
Microscopic reversibility: Markov chains

Equilibrium:

$$\pi_{ij}\lambda_j = \pi_{ji}\lambda_i \quad \lambda_i = e^{-\beta(E_i - F)}$$

External work:

Non homogeneous dynamics $\pi = \pi(t)$ because of the time dependent protocol of the external force



λ is the invariant distribution of $\pi(t)$ for every t
i.e. the unperturbed dynamics preserves the equilibrium distribution

Transition matrix of the reversal path

$$\pi_{ij}(\tau - t)\lambda_j(\tau - t)_{x(\tau-t)} = \widehat{\pi}_{ji}(t)\lambda_i(\tau - t)_{x(\tau-t+1)}$$

$$\begin{aligned} \frac{P(traj)}{P(-traj)} &= \frac{P[x(0), \pi]}{P[\widehat{x}(0), \widehat{\pi}]} = \\ &= \frac{\pi_{x(1)x(0)} \cdots \pi_{x(\tau)x(\tau-1)}}{\lambda_{x(\tau)}^{-1}(\tau - 1)\pi_{x(\tau)x(\tau-1)}(\tau - 1)\lambda_{x(\tau-1)}(\tau - 1) \cdots \lambda_{x(1)}^{-1}(0)\pi_{x(1)x(0)}(0)\lambda_{x(0)}(0)} = \\ &= \prod_{t=0}^{\tau-1} \frac{\lambda_{x(t+1)}(t)}{\lambda_{x(t)}(t)} = e^{-\beta \sum_{t=1}^{\tau-1} [E(t)_{x(t+1)} - E(t)_{x(t)}]} = e^{-\beta Q} \end{aligned}$$

$$\boxed{\frac{P[traj]}{P[-traj]} = e^{-\beta Q[x]}}$$

Microscopic reversibility

The FR for systems in contact with two heat baths

Equilibrium: $\pi_{ij}\lambda_j = \pi_{ji}\lambda_i \longrightarrow e^{\frac{q}{T}} \pi_{ij}^q = \pi_{ji}^{-q} \quad q = E_i - E_j$
 $\lambda_i = e^{-\beta(E_i - F)}$

Two temperatures: $e^{\frac{q_1}{T_1} + \frac{q_2}{T_2}} \pi_{ij}^{q_1, q_2} = \pi_{ji}^{-q_1, -q_2}$ Generalized detailed balance

$$\frac{Prob(traj)}{Prob(-traj)} = \frac{\prod_{i=1}^{\tau-1} \pi^{q_{1,i}, q_{2,i}}(C_{i+1}, C_i) \prod_{i=1}^{\tau-1} P_{H,i}}{\prod_{i=1}^{\tau-1} \pi^{-q_{1,i}, -q_{2,i}}(C_i, C_{i+1}) \prod_{i=1}^{\tau-1} P_{H,i}} =$$

$$e^{-\sum_{i=1}^{\tau-1} [\frac{q_{1,i}}{T_1} + \frac{q_{2,i}}{T_2}]} = e^{-\frac{Q_1}{T_1} - \frac{Q_2}{T_2}} = e^{-\frac{Q_1}{T_1} - \frac{\Delta E - Q_1}{T_2}} = e^{-Q_1(\frac{1}{T_1} - \frac{1}{T_2}) - \frac{\Delta E}{T_2}}$$

.....

$$\tau \rightarrow \infty \Rightarrow Q_1 \gg \Delta E \quad \text{and} \quad \sum_{traj|Q_1} \longrightarrow \boxed{\frac{P(Q_1)}{P(-Q_1)} = e^{-(\beta_1 - \beta_2)Q_1}}$$

Two models: static and dynamic

Transition rates: $\pi(C', C) = \begin{cases} ke^{-\beta_i \Delta E(C', C)} & \Delta E(C', C) > 0 \\ k & \text{otherwise} \end{cases}$

$$k \ni \sum_{C'} \pi(C', C) = 1$$

Single spin-flip & Kawasaki

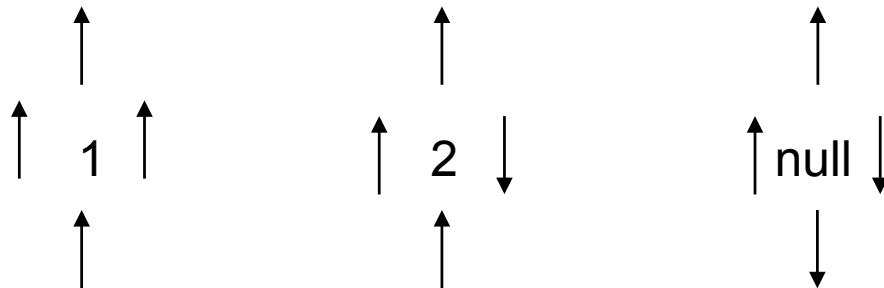
$$i = \begin{cases} 1 & 1 < x \leq \frac{L}{2} \\ 2 & \frac{L}{2} < x \leq L \end{cases}$$

Dynamic model

$$i = \begin{cases} 2 & \frac{1}{2} \left| \sum_{\langle j \rangle i} \sigma_j \right| = 1 \\ 1 & \frac{1}{2} \left| \sum_{\langle j \rangle i} \sigma_j \right| = 2 \end{cases}$$

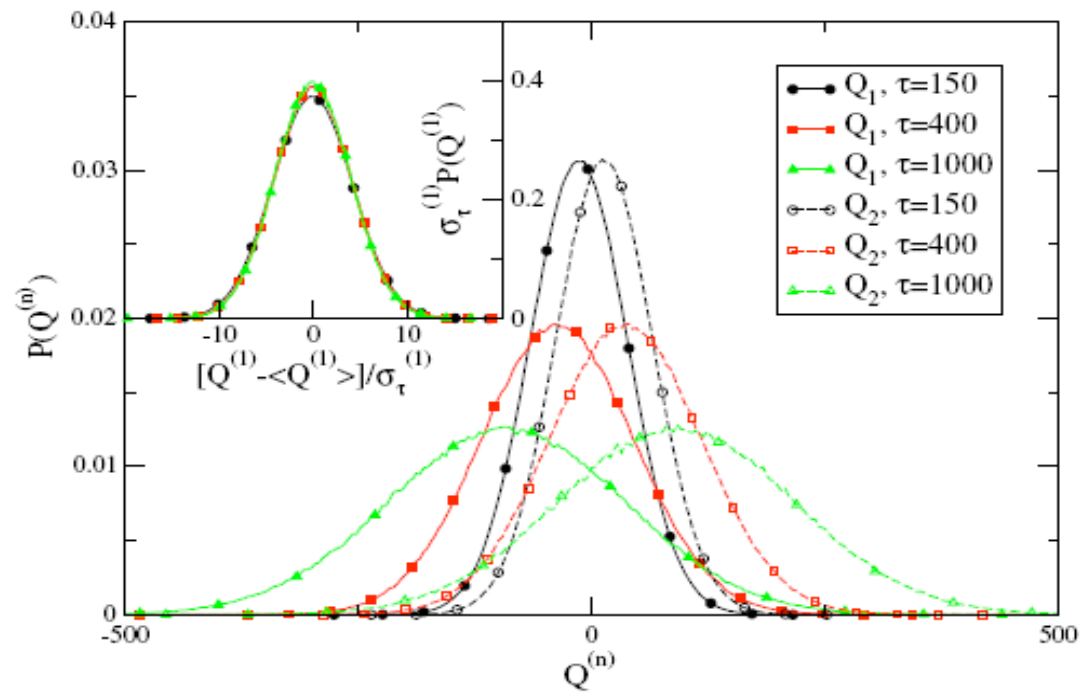
with $\beta_2 < \beta_1$

- Single spin-flip dynamics
- Kawasaki dynamics: spin-flip of randomly chosen pairs of first neighbour opposite spins
- Dynamic (Mendez et al.) model

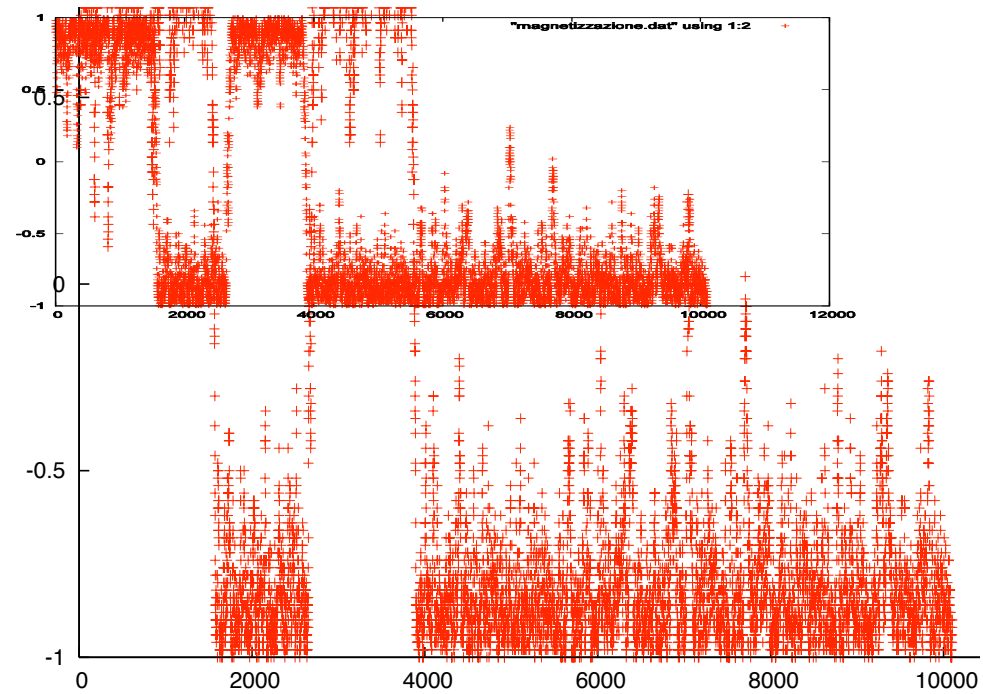


Ising model distribution

Above T_c : $T_1=2.9$ and $T_2=3$, $L=10$



Magnetization jumps



Fluctuation-dissipation limit

$$T_2 - T_1 \rightarrow 0^+$$

$$\frac{\langle Q_1^2 \rangle_{eq}}{\tau} \rightarrow D \quad \text{for} \quad T_1 = T_2 \longrightarrow D \text{ is the fluctuation coefficient}$$

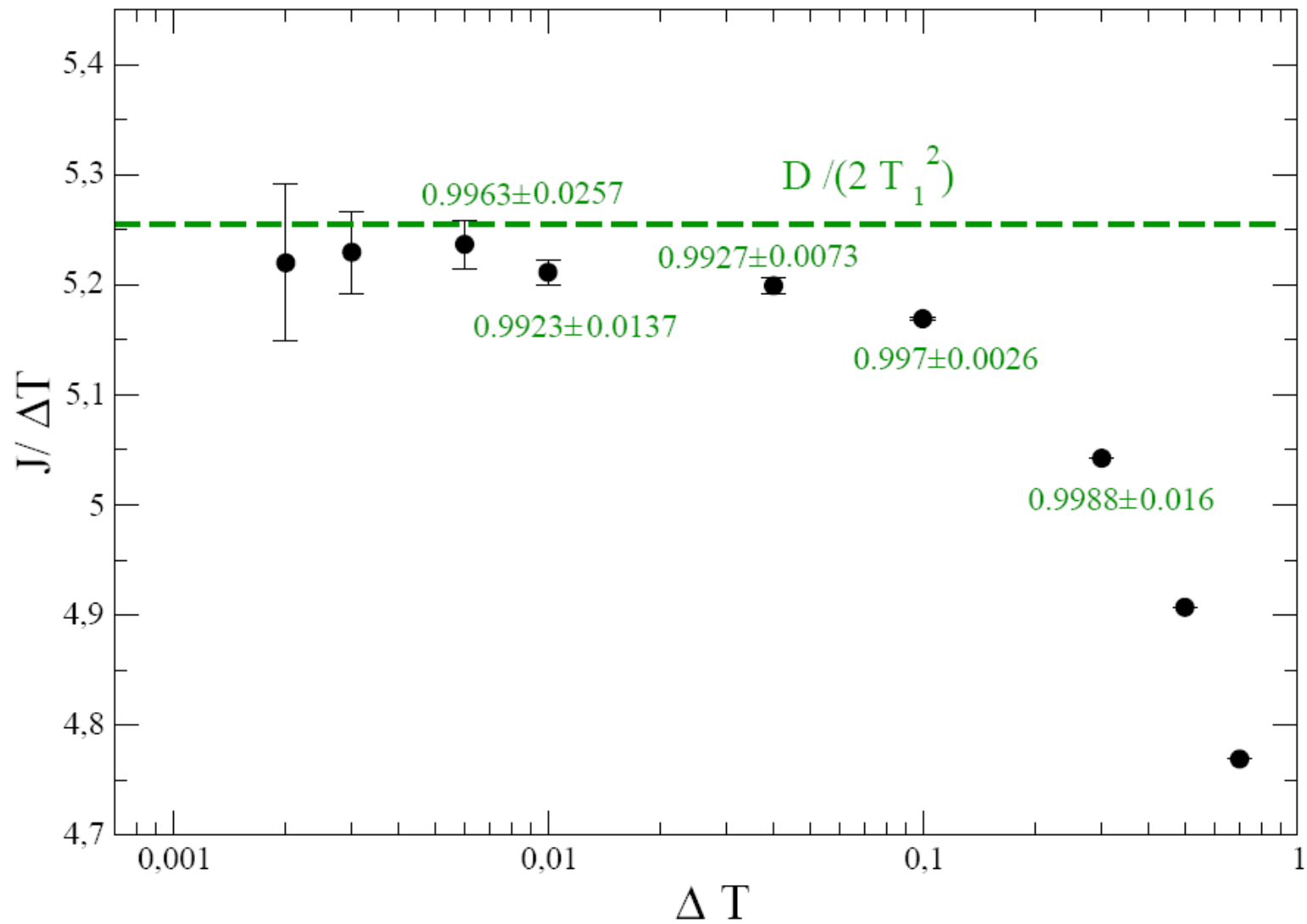
$$\frac{\langle Q_1 \rangle}{\tau} \rightarrow (T_1 - T_2)j \quad \text{for} \quad T_2 - T_1 \rightarrow 0^+ \longrightarrow j \text{ is the linear response}$$

With these definition and exploiting the FR for gaussian fluctuations:

$$\lim_{T_2 - T_1 \rightarrow 0^+} \frac{\mu_1}{\tau(T_1 - T_2)} = \frac{\sigma_{eq}^2}{2T_1^2\tau} = \frac{D}{2T_1^2}$$

$$\frac{j}{\Delta T} = \frac{D}{2T_1^2} \quad \text{Einstein relation for a two temperature system}$$

Fluctuation-dissipation limit



Corrections and scaling

Defining ϵ as the correction to the slope 1 (the FR) recovered for $\tau \rightarrow \infty$

$$\frac{P(Q_1)}{P(-Q_1)} = e^{-Q_1(\beta_1 - \beta_2)(1 - \epsilon)}$$

$\frac{P(Q_1)}{\text{gaussian}}$ + $\frac{\mathcal{P}^{staz}(\tau)}{\mathcal{P}^{staz}(0)}$ One free parameter includes the form of this ratio, which contains the interaction between the two bulk at different temperatures

CORRECTIONS

$$\epsilon^{(n)} \Delta\beta^{(n')} \simeq -\frac{\langle Q^{(n)}(\tau) \rangle}{(\sigma_\tau^{(n)})^2} \mp \sqrt{\left(\frac{\langle Q^{(n)}(\tau) \rangle}{(\sigma_\tau^{(n)})^2} \right)^2 + \frac{v_{\Delta E}^2}{(\sigma_\tau^{(n)})^2} (\Delta\beta^{(n')})^2}$$

SCALING

$$\lim_{\tau \rightarrow \infty} \epsilon^{(n)} = \frac{\Delta\beta^{(n')} v_{\Delta E}^2 (\sigma_\tau^n)^2}{2 \langle Q^{(n)}(\tau) \rangle^2} \sim \frac{v_{\Delta E}^2}{(\sigma_\tau^n)^2} \sim \frac{1}{\tau}$$

Corrections trend with time and size

$$\underline{v_{\Delta E}^2 \sim \sigma_{\Delta E}^2 \sim L^2}$$

	L	τ
$v_{\Delta E}^2$	<u>L^2</u>	<u>constant</u>
σ_{τ}^2	static L dynamic <u>L^2</u>	<u>τ</u>

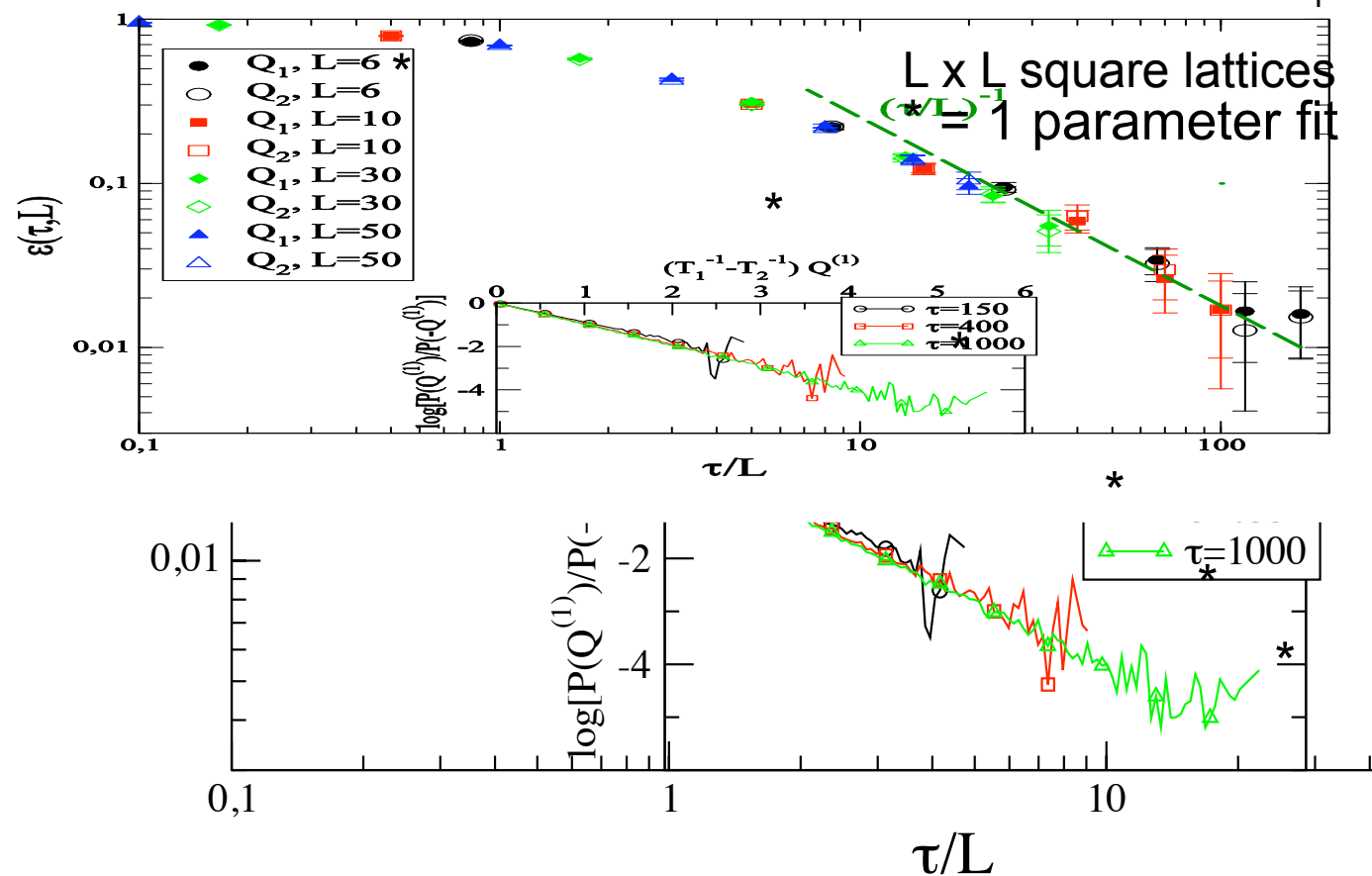
$$FR_{\tau \rightarrow \infty} + \text{gaussianity} : \frac{\langle Q_{\tau} \rangle}{\sigma_{\tau}^2} = -\frac{\beta_1 - \beta_2}{2} = \text{constant with } L \text{ and } \tau$$

$$\sigma_{\tau}^2 \sim_{L,\tau} \langle Q_{\tau} \rangle \sim \text{number of interface links} \propto \begin{cases} \text{static} & L \\ \text{dynamic} & L^2 \end{cases}$$

$$\epsilon(\tau, L) \sim_{\tau \rightarrow \infty} \frac{v_{\Delta E}^2}{\sigma_{\tau}^2} \sim \begin{cases} \text{static} & \frac{L^2}{L_{\tau}} = \frac{L}{\tau} \\ \text{dynamic} & \frac{L^2}{L^2 \tau} = \frac{1}{\tau} \end{cases}$$

Scaling Ising above T_c

Above T_c : $T_1=2.9$ and $T_2=3$

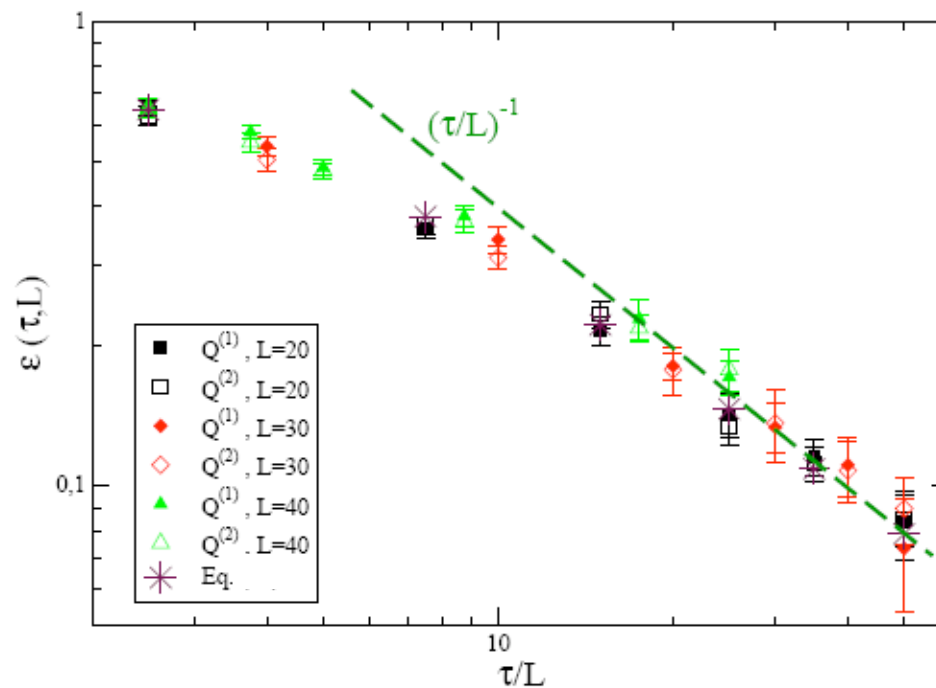


$$\epsilon(\tau, L) = 1 - \text{slope}$$

$$\epsilon(\tau, L) = f(\tau/L) \sim 1/x$$

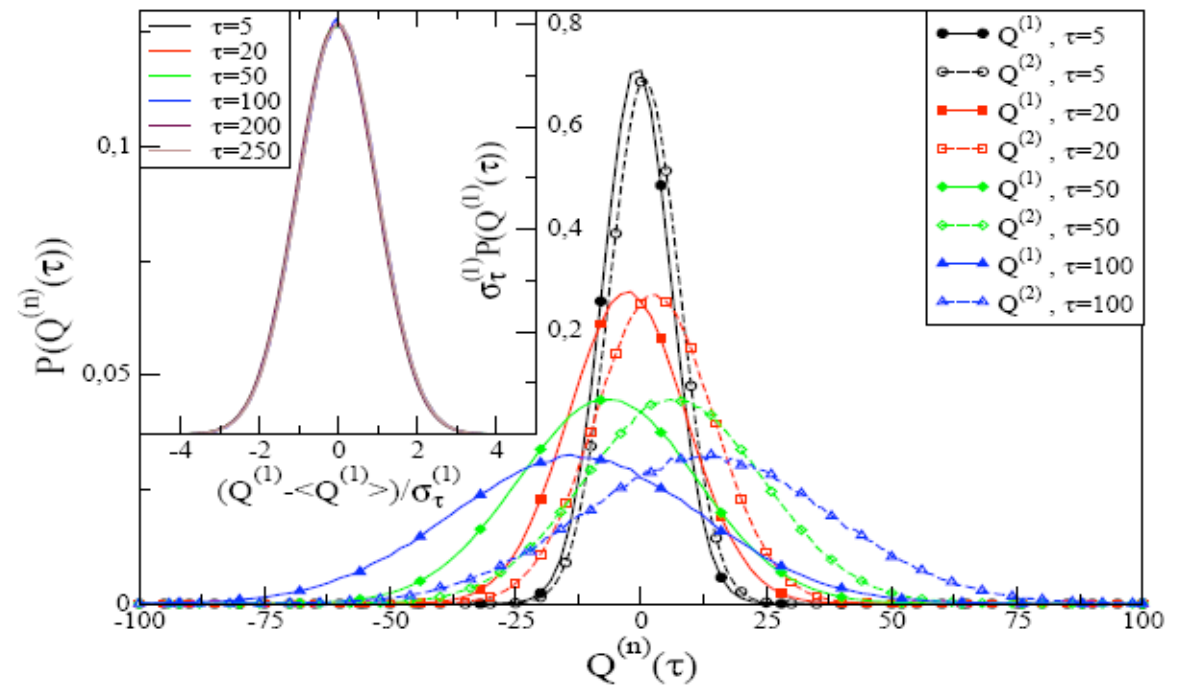
Kawasaki corrections and scaling

Above T_c : $T_1=2.9$ and $T_2=3$



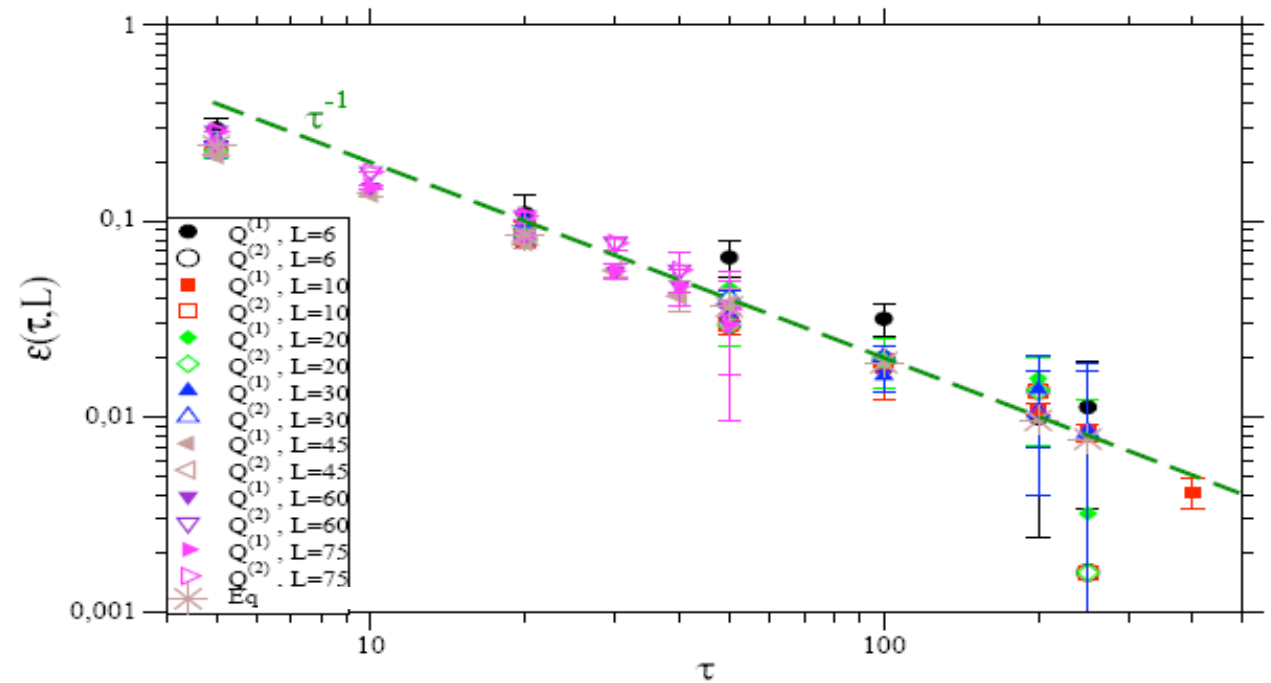
Dynamic model distributions

Above T_c : $T_1=3.$ and $T_2=3.1$, $L=10$

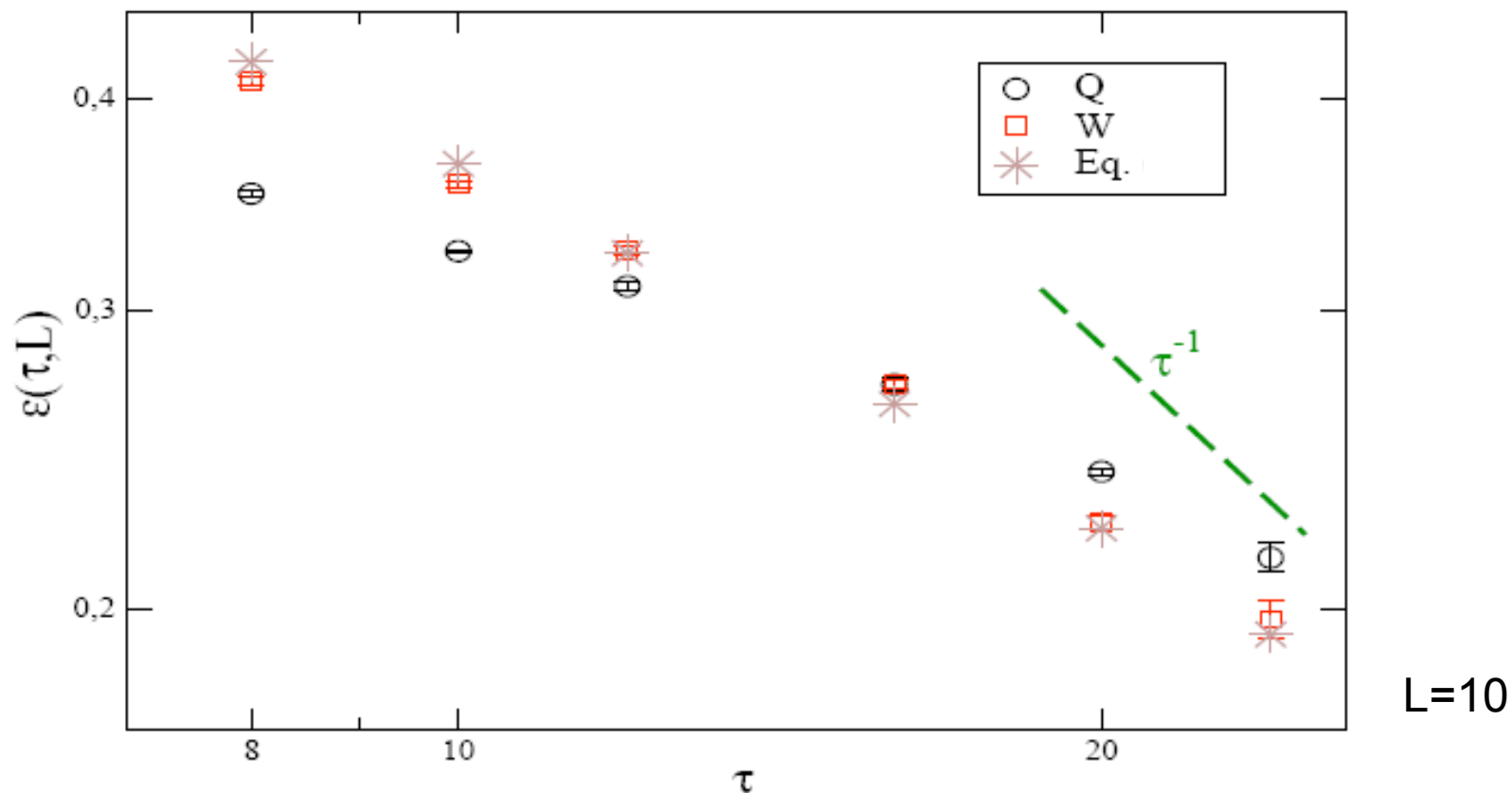


Dynamic model corrections and scaling

Above T_c : $T_1=3.$ and $T_2=3.1$



Work corrections and scaling in an Ising system with shear



$$\epsilon^{(\mathcal{O})} = \mp \frac{T \langle \mathcal{O}(\tau) \rangle}{(\sigma_{\tau}^{(\mathcal{O})})^2} + T \sqrt{\left(\frac{\langle \mathcal{O}(\tau) \rangle}{(\sigma_{\tau}^{(\mathcal{O})})^2} \right)^2 + \frac{v^2}{(\sigma_{\tau}^{(\mathcal{O})})^2}}$$

- for $\mathcal{O} = \mathcal{W}$
+ for $\mathcal{O} = \mathcal{Q}$.

Conclusions

- The FR is realized also below T_c when the PDFs are not gaussian (in a way independent by the linear response theory)

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Thank you!